

## GreenTrans

## Mobile Robot

Technical Support by China Motor Corp.













GreenTrans Corporation







## LEATURES 3

- GreenTrans is able to help design user's turnkey system solution and integration the system with user's control system such as MES.
- Equipped with SLAM technology, the vehicle is able to navigate fully autonomously.
- The vehicle is supplied directly with power from Li-ion batteries.
- The GreenTrans MR is able to move omni-directionally; it is able to move back and forth, sideways and diagonally.

actory nowadays requires not only efficiency and stability but also flexibility and mobility. The GreenTrans Mobile Robot is an intelligent vehicle with self-navigating ability designed for rapid changing environments in factories and warehouses for material handling. Unlike conventional AGV, GreenTrans Mobile Robot applies the latest SLAM technology for navigation, and it is able to work without inductive magnets and wires, triangulation reflectors and optical guidance, offering true flexibility in facility layout planning and saving facility modification costs.

reenTrans Corporation is specialized in the development of mobile robot applications in logistics field. A wholly owned subsidiary company of China Motor Corporation, one of Taiwan's leading automobile manufacturers, GreenTrans Corporation is endeavor to provide high quality Mobile Robots to the users island wide.

Model	MR100	MR150 <sup>①</sup>
Dimensions(L*W*H)	1,154mm*654mm*700mm	1,154mm*654mm*453mm
Grabbing Capacity	12KG <b>2</b>	-
Loading Capacity	<del>-</del>	150KG
Patrol Speed	Max. 50m/min	
Positioning Accuracy	+/- 10mm	
Turing Radius	min. 600mm @30m/min	
Motion mode	Forward, Backward, Rotating <sup>,</sup> Diagonal moving	
Driver System	Differential Drive	
Weight	242KG	150KG
Battery	Lithium iron 12V/35Ah*4	

- ME(Mobile E-Rack) is the application of MR150 with E-Rack
- 2 Depending on the gripping capacity of the Robot.
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- ◆ Specifications regarding the AGV's movement may be limited or influenced by surrounding conditions.
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